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#### Università degli Studi di Padova



#### GMNet: Graph Matching Network for Large Scale Part Semantic Segmentation in the Wild

Umberto Michieli, Edoardo Borsato, Luca Rossi, Pietro Zanuttigh

umberto.michieli@dei.unipd.it



### **Semantic Segmentation - Definition**

Assign to each pixel a label representing the class to which the pixel belongs.

- Dense task
- Deep learning revolutionized the field (autoencoder models) [1]





[1] Long et al., "Fully convolutional networks for semantic segmentation", CVPR 2015.



#### **Multi-Class Part Parsing**

 $\rightarrow$  Learn multiple parts of multiple objects





## **Coarse-to-Fine Learning**

Transfer knowledge form a coarse problem to a finer one

**Spatial level** coarse-to-fine: object-level classes split into their parts

 $\rightarrow$  learn multiple parts of multiple objects







#### Annotations object-level



Annotations part-level



First idea (baseline): just train a network on all the different parts

Low results, 2 main reasons:

Object-level ambiguity: corresponding parts in different semantic classes often share similar appearance









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Sheep legs



Cow legs





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 $\succ$  object-level guidance via semantic embedding network  ${\mathcal S}$ 

> auxiliary reconstruction module from parts to objects

Part-level ambiguity: limited local context is captured

> graph-matching module to preserve relative spatial relationships

between ground truth and predicted parts.





### **Graph Matching Module**



Normalized matrices  $\rightarrow$  *proximity ratios* 

Graph-Matching loss: 
$$\mathcal{L}_{GM} = ||\mathbf{M}^{GT} - \mathbf{M}^{pred}||_F$$



#### Dataset – VOC2012 Pascal Parts



PASCAL-VOC 2012: 10103 images: 4998 train and 5105 validation 

- 21 object-level classes
- Pascal-Part-58 [1] and Pascal-Part-108 [2,3]

[1] Zhao et al., "Multi-class Part Parsing with Joint Boundary-Semantic Awareness", iCCV 2019 [2] A. Gonzalez-Garcia et al., "Do Semantic Parts Emerge in Convolutional Neural Networks?", IJCV, 2017 [3] Michieli et al., "GMNet: Graph Matching Network for Large Scale Part Semantic Segmentation in the Wild", ECCV, 2020



#### Experiments – Pascal 58

RGB	Annotation	Baseline	BSANet*	GMNet (ours)

Method	mloU	Avg.	
SegNet	24.4	26.5	
FCN	42.3	44.9	
DeepLab v1	49.9	51.9	
DRN D 38	50.0	50.9	
DRN D 105	53.0	53.0	
BSANet*	58.2	58.9	
Baseline (DeepLab v3)	54.4	55.7	
GMNet (ours)	59.0	61.8	

\* It is the only other method for multi-class part parsing and uses the same architecture (DeepLab v3+, ResNet-101)



#### Experiments – Pascal 108

RGB	Annotation	Baseline	BSANet*	GMNet (ours)	Method	mloU	Avg.
					SegNet	18.6	20.8
					FCN	31.6	33.8
					DeepLab v1	35.7	40.8
					DRN D 38	39.1	41.9
					DRN D 105	39.5	41.0
		- And			BSANet*	42.9	46.3
				- 0	Baseline (DeepLab v3)	41.3	43.7
6668			<b>~~~</b>		GMNet (ours)	45.8	50.5

\* It is the only other method for multi-class part parsing and uses the same architecture (DeepLab v3+, ResNet-101) Multi-class Zhao et al., "Part Parsing with Joint Boundary-Semantic Awareness", iCCV 2019



Semantic segmentation of **multiple parts** from **multiple objects** 

#### Contributions:

- Object-level semantic embedding network guides part-level decoding stage
- Graph-matching module for accurate relative localization of semantic parts
- GMNet achieves new state-of-the-art performance on Pascal-Part-58 and 108

Paper website: <a href="https://lttm.dei.unipd.it/paper\_data/GMNet">https://lttm.dei.unipd.it/paper\_data/GMNet</a>

Code: <a href="https://github.com/LTTM/GMNet">https://github.com/LTTM/GMNet</a>

ArXiv: https://arxiv.org/abs/2007.09073

Contact: <a href="mailto:umberto.michieli@dei.unipd.it">umberto.michieli@dei.unipd.it</a>

<u>Michieli U.</u>, Borsato E., Rossi L. and Zanuttigh P., "GMNet: Graph Matching Network for Large Scale Part Semantic Segmentation in the Wild," ECCV 2020.





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